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#### **RSE2107A – Lecture 8**

**Deep Learning** 

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#### **O** What is deep learning

02 Deep Learning in CV



#### Workflow for training & deployment of DL models

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## Deep Learning





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## Artificial Intelligence

- Enables machines to think without any human intervention
  - AI Systems falls into these 3 types
    - Artificial Narrow Intelligence (ANI)
      - Goal-oriented and programmed to perform a single task
    - Artificial General Intelligence (AGI)
      - Allows machines to learn, understand, and act in a way that is indistinguishable from humans in a given situation
    - Artificial Super Intelligence (ASI)

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Capable of exhibiting intelligence that surpasses humans



### Machine Learning

- Uses statistical learning algorithm to build smart systems
- ML Systems can learn and improve automatically without explicitly being programmed
- Classified into 3 types
  - Supervised
  - Unsupervised
  - Reinforcement learning





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### Deep Learning

- Associated with learning from examples
  - DL Systems help computer model to filter input data through layers to predict and classify information
  - Similar to ML which requires large amount of data to learn and make informed decisions
  - DL Network architectures
    - Convolutional Neural Networks
    - Recurrent Neural Networks
    - Recursive Neural Networks





## Advantages of DL over ML ×

- Feature Extraction
  - ML algorithm requires pre-processing phase before being applied to data such as images, text, CSV
    - Example: To determine cat or dog using ML, we need to extract features like size, shape, etc and give these features to ML model to identify
  - DL, however, is capable of identifying these features without the need for features extraction, as it is capable of classifying it on its own



#### Weston Robot Advantages of DL over ML

#### Machine Learning



Input

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Feature extraction + Classification



Output



## Advantages of DL over ML ×

#### Big Data

- Accuracy of ML will stop increasing at a certain point in time, even with an increasing amount of data
- $\circ~$  DL however, will increase its accuracy with increasing data
  - Like how brain works





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## Neural Network



#### Weston Robot What are neural networks? ×

- Neural networks are a subset of machine learning and are at the heart of deep learning algorithms. Their name and structure are inspired by the human brain.
  - Also known as artificial neural networks (ANNs), they comprise of an input layer, one or more hidden layers, and an output layer.
    - $\circ$  input layers take in raw inputs from a dataset

- hidden layers take their inputs from the output of the previous layer, processes it and passes its own output onto the next layer.
- output layers are the last layer of the ANN and will make a final prediction of the initial inputs might be.



## Deep learning neural networks ×

 A neural network that consists of more than three layers, which would be inclusive of the inputs and the output, can be considered a deep learning algorithm.

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#### DEEP NEURAL NETWORK

## How do neural networks work? - Layers ×

 Each layer in a neural network are made up of multiple nodes (neurons), each connected to every node in the next layer.

- Each node represents an independent variable that affects the output that the neural network model is trying to predict.
  - Eg. A model that can predict the price of houses(output) will have input variables (nodes in the first input layer) such as age, house space, surrounding amenities, etc.



## How do neural networks work? - Nodes ×

 Nodes are the smallest computational unit in a neural network, each doing a fixed mathematical formula (can differ across nodes).

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 Each node calculates an output based on the weighted (W) inputs (X) from the previous layer's nodes' outputs and a given bias using its own formula (activation function).



## How do neural networks work? - Nodes ×

#### Inputs (x)

- Outputs from nodes in previous layer
- Weights (w)
  - Determines how much each input affects the output of the given node
  - Higher == Stronger
- Biases (b)
  - Used to independently adjust the weighted sums of the inputs.
    Helps the network to best fit the dataset.
- Activation Function (f)
  - Computes the output of the node
- Output =  $f(\Sigma_i(w_i \cdot x_i) + b)$



## How do neural networks work? ×



 $8px \times 8px = 64$  pixels



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## How do neural networks work? ×



 $8px \times 8px = 64$  pixels



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#### Weston Robot CNNs - Convolutional Neural Nets ×

- A convolutional neural network (CNN) is a type of artificial neural network used in image recognition and processing that is specifically designed to process pixel data.
  - The advancements in Computer Vision with Deep Learning has been constructed and perfected with time, primarily over one particular algorithm a Convolutional Neural



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#### Weston Robot CNNs - Convolutional Neural Nets ×



- The Convolution layer is the core building block of a Convolutional Network that does most of the computational heavy lifting.
- The role of the Convolution layer is to reduce the images into a form which is easier to process, without losing features which are critical for getting a good prediction.
- This processing is done by a kernel/filter.

## CNNs - Convolutional Neural Nets ×



Convoluting a 5x5x1 image with a 3x3x1 kernel to get a 3x3x1 convolved feature



Convolution Operation with Stride Length = 2

- The objective of the Convolution
  Operation is to extract the high-level features such as edges and contours, from the input image.
- With added layers, the model adapts to the High-Level features as well, resulting in a network which has a better understanding of the images in the dataset.

#### Weston Robot **CNNs** - Convolutional Neural Nets

- There are several other layers and functions that can be found in general CNN model architectures. These include
  - **Pooling layers**  $\bigcirc$

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- Activation layers/functions
- Fully Connected Layers 0
- On top of these there are Loss Functions.
- Finally we have our optimization algorithm. The most commonly used, is the Stochastic Gradient Descent (SGD).





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## Deep Learning in CV



## Types of Image Recognition ×

# person, sheep, dog

(a) classification

(b) detection

(c) segmentation



#### Classification

- Type of labeling where image/video is assigned certain concepts/categories
  - Goal is to answer "What is there in this image/video"
  - Does not tell where the objects are located at nor how many there are, just that it exists in the given image





### Segmentation

- Type of labeling where *each pixel* of an image is labeled with given concepts
  - simplifies an image or changing how it is presented to the model, making it easier to analyse
  - Provides the exact outline of an object within an image
  - Requires object classification and object detection to have took place before segmentation can be used
  - Useful if there is a need to ignore the background of an image







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### Typical Object Detection Workflow



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- Refers to detecting instances of semantic objects of a certain class (such as humans, buildings, or cars) in digital images and videos.
  - Object detection has applications in many computer vision tasks such as face recognition, vehicle counting and tracking objects.





## How is Object Detection done? ×

- Digital images are represented as array of integer values
- Image (defined as an array of values) is passed through a neural network
- Neural network makes predictions on the image & d boxes to identify and locate objects with a certain pr



## Object Detection Workflow ×













## 1. Data collection - Methods ×

- Method 1: Taking from online datasets
  - Many open source datasets available online
  - Can come fully/partially annotated, or not annotated at all
  - Eg. Kaggle, COCO dataset, Github etc...
  - Method 2: Self-source data

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Taking Photos & Videos



#### Considerations

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- Clearly define the object types to identify
  - General object types are hard for the model to distinguish
    - Eg. Trash can come in many forms, which makes it hard to distinguish
  - Use types where the objects have largely similar attributes
    - Eg. Splitting trash into plastic bottles, paper cups, drink cans etc
  - This will help in improving the accuracy of your model



#### Considerations

How much data to collect?

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- Collecting more varied data is better for most cases
  - However, if your model is only required to identify objects in fixed scenarios/specialised environments, varied data can instead decrease the accuracy of the model.
- Dependent on quantity of object instances in each image, rather than the total number of images
- Best to maintain equal amounts of images for each class to prevent class imbalance
  - Otherwise, it can result in low accuracy for infrequent objects







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### Annotation of images

- Object detection is a supervised learning problem, where our model has to be trained on annotated examples.
  - Used to identify objects and tell the computer where the object is in the image
  - Bounding boxes are drawn to identify & locate the objects in the images
  - Use labelling tools for annotation of images
    - $\circ$  Roboflow
    - CAT
    - LabelImg





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### Annotation of images

- Good practices
  - Tight-Fitting bounding boxes
  - Little/No overlap for bounding boxes
  - Cover full size of the image









## Image Pre-processing

- Technique that suppresses undesired distortions or enhances some image features relevant for further processing and analysis task.
  - Used to remove unwanted/noisy data from the images and possibly reduce training time
  - Examples
    - Image Resizing
    - Cropping of images
    - Image Auto-Orientation



## Data Augmentation

- Technique that applies variations to the images within the dataset and appends them to it
  - Used to increase the size of our our training dataset
  - This helps us to create a more robust and generalized model
  - Examples:

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- Adjusting Brightness & Exposure levels
- Blurring/Cropping parts of the image









### Train-Test Split

- Refers to taking a dataset and splitting it into 2 subsets Train & Test dataset
  - Used to estimate the performance of the model on new data: data not used to train the model
  - The train dataset is used to train the model while the test dataset is used to evaluate the model
  - Minimizes overfitting as the model is evaluated on new data











### 3. Model Training

- The process which a Deep Learning Algorithm is being fed with sufficient training data to learn from, which helps it to identify and learn good values for all attributes involved
  - Inputs from the training dataset are fed into the model, and training is done based on the deviation of the processed result from the documented result.
  - Consistent training can significantly improve the prediction rate of the model
  - 2 key methods:

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- Creating a Deep Learning Algorithm
- Using a pre-trained Deep Learning Algorithm



### Creating a Model

- Neural Network is usually loaded with random weights
  - Upon each iteration of the training dataset running through the model, the weights will be recalibrated and adjusted, based on the difference between the predicted and actual output.
  - Not recommended for beginners as it takes a significantly longer amount of time to train a model from scratch



## Using Pre-Trained Models ×

- Also known as Transfer Learning, we can use pre-trained models as the base for training our object detection model
  - Pre-Trained Model examples include:
    - YOLOV5
    - Resnet50
    - EfficientNet
    - and more....
  - Different pre-trained models are more suited for different use cases.
    - Example: Resnet50 is more accurate compared to the EfficientNet, however the Resnet50 is computationally more expensive compared to the EfficientNet.



### How to train?



- Make use of Object Detection APIs
  - YOLOV5 API using PyTorch
  - TensorFlow Object Detection API
  - Take note of configurable training parameters:
    - How many epochs to run?
      - Epochs refers to the number of runs the algorithm goes through the training set
      - Running more epochs usually results in better training results
      - However, running too many epochs might result in overfitting of the model
    - Image Size used for training
      - If too big, it will stretch the images and cause them to lose its aspect ratio
      - If too small, images might not have enough features for model training and learning
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### 4. Model Evaluation

- Use the model to run inferences of test images & videos
  - Use training metrics to determine the accuracy of the model
  - Training metrics visualization tools
    - Weights & Biases
    - Tensorboard



## Mean Average President (mAP) ×

- A popular metric that tells you how precise your classifier is (how many instances it classifies correctly), as well as how robust it is (it does not miss a significant number of instances), where it computes the average precision value for recall value over 0 to 1.
  - Precision refers to the number of correct positive results (True Positives) divided by the number of positive results predicted by the classifier (True & False Positives).
  - Recall refers to the number of correct positive results (True Positives) divided by the number of \*\*all\*\* relevant samples (True Positives & False Negatives)













## 5. Model Deployment

- If user is unsatisfied with the performance of the model, it is possible to re-train on the same model once again
  - Else, the model is then ready to be exported for deployment
  - The newly trained model can be exported into numerous formats for different use cases, including:
    - Tensorflow-Lite
      - Running inference models on edge devices
    - Nvidia-DeepStream
      - Can use for running inference models for Nvidia controllers (ie. jetson nano etc)



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## Appendix

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- Popular Online Datasets
  - Kaggle Dataset <u>https://www.kaggle.com/datasets</u>
  - COCO Dataset <u>https://cocodataset.org/#home</u>
  - Object Detection APIs

- Tensorflow <u>https://tensorflow-object-detection-api-tutorial.readthedocs.io/en/latest/</u>
- YOLOv5 <u>https://github.com/ultralytics/yolov5/releases</u>